

10/4/2021

last time:

- double contained proofs
- linear independence.

Def: vectors $\{v_1, \dots, v_k\}$ are a basis for V if the following two statements are satisfied:

→ $\text{Span}(v_1, \dots, v_k) = V.$

→ $\{v_1, \dots, v_k\}$ are linearly independent.

Ex: we have shown that:

$\text{Span}\left(\begin{bmatrix} -1 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = \mathbb{R}^2$ and that

$\left\{\begin{bmatrix} -1 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}\right\}$ are linearly independent,
so we say that these two vectors
form a basis for $\mathbb{R}^2$.

Ex: Consider the set of vectors

$\left\{\begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}\right\}.$

~~Question~~

Are these vectors linearly independent?

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Let's consider an arbitrary linear combination of these vectors and set it equal to 0:

$$\alpha_1 \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} + \alpha_2 \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} + \alpha_3 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}.$$

This can be written in matrix form:

$$\begin{pmatrix} -1 & 2 & 1 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}.$$

Applying Gaussian elimination:

$$\leadsto \begin{pmatrix} -1 & 2 & 1 \\ 0 & 1 & 1 \\ 0 & 2 & 2 \end{pmatrix} \begin{pmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}.$$

$$\leadsto \begin{pmatrix} -1 & 2 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}.$$

So, α_3 is a free variable, let's set it to 1: $\alpha_3 = 1$, which implies $\alpha_1 = \alpha_2 = 1$. $\leadsto$

So we have a "nontrivial" linear combination

$$(1) \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} + (1) \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} + (-1) \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}.$$

That results in the zero vector,
implying that $\left\{ \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\}$
are linearly dependent.

Def: let V be a vector space.

The number of vectors in a basis
for V is called the dimension of
 V and is denoted $\dim(V)$.

Ex: We saw: $\left\{ \begin{pmatrix} -1 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$ is

a basis for $\mathbb{R}^2$, ~~so~~ so we
conclude $\dim(\mathbb{R}^2) = 2$.

Thm: (should be stated before basis
definition)

If $\{u_1, u_2, \dots, u_p\}$ and $\{v_1, \dots, v_q\}$
are bases for U , then $p = q$.

Remark: Notice that the definition of a basis can be rewritten in matrix form:

$\{\underline{v}_1, \dots, \underline{v}_k\}$ is a basis for $\mathcal{U}$,

if we construct a matrix

$$\underline{V} = \begin{pmatrix} | & | & \dots & | \\ \underline{v}_1 & \underline{v}_2 & \dots & \underline{v}_k \\ | & | & \dots & | \end{pmatrix}$$

and

$$\rightarrow R(\underline{V}) = \mathcal{U}.$$

$$\rightarrow N(\underline{V}) = \{\underline{0}\}.$$

Ex: Is $\left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right\}$ a basis for $\mathbb{R}^2$?

We need to check the above two equalities, with the matrix

$$\underline{V} = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}.$$

→ Show $R(\underline{v}) = \mathbb{R}^2$

By double containment.

Take $\underline{x} \in R(\underline{v})$. So

$$\underline{x} = \gamma_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} + \gamma_2 \begin{pmatrix} 1 \\ -1 \end{pmatrix}.$$

Clearly $\underline{x} \in \mathbb{R}^2$, so $R(\underline{v}) \subset \mathbb{R}^2$.

Take $\underline{y} \in \mathbb{R}^2$. We want to find $\alpha_1, \alpha_2 \in \mathbb{R}$ so that

$$\underline{y} = \alpha_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} + \alpha_2 \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} \alpha_1 \\ \alpha_2 \end{pmatrix}.$$

⇒ we want to solve: $\begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} \alpha_1 \\ \alpha_2 \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$

Row reduction or Gaussian elimination:

$$\begin{pmatrix} 1 & 1 \\ 0 & -2 \end{pmatrix} \begin{pmatrix} \alpha_1 \\ \alpha_2 \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 - y_1 \end{pmatrix}$$

$$\Rightarrow \alpha_2 = \frac{y_1 - y_2}{2}$$

$$\Rightarrow \alpha_1 + \alpha_2 = y_1 \Rightarrow \alpha_1 = y_1 - \left(\frac{y_1 - y_2}{2}\right) = \frac{y_2 + y_1}{2}.$$

$$\text{So } y = \left(\frac{y_2 + y_1}{2} \right) \begin{pmatrix} 1 \\ 1 \end{pmatrix} + \left(\frac{y_1 - y_2}{2} \right) \begin{pmatrix} 1 \\ -1 \end{pmatrix},$$

implying $y \in R(\underline{V})$ and so $\mathbb{R}^2 \subset R(\underline{V})$.

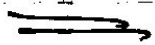
→ show $N(\underline{V}) = \{ \underline{0} \}$.

$$\text{look at } \underline{V} \underline{z} = \underline{0} \Leftrightarrow \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}.$$

Gaussian elimination gives:

$$\begin{pmatrix} 1 & 1 \\ 0 & -2 \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow z_1 = 0, z_2 = 0, \text{ so } N(\underline{V}) = \{ \underline{0} \}.$$



Question: Given a set of vectors, put into a matrix, how do we compute bases for the range, and Nullspace of this matrix.

Def: Given $\underline{A} \in \mathbb{R}^{m \times n}$ and $\text{ref}(\underline{A}) = \underline{U}$, the pivots are the leading nonzeros of $\underline{U}$.