

→ last time
→ FTA and linear
least squares; derived
normal equations.

10/20/2021

Again, our setup is $\underline{A} \in \mathbb{R}^{m \times n}$, $m > n$,

and we want to minimize

$$\| \underline{A} \underline{x} - \underline{b} \|_2^2.$$

First step... decompose $\underline{b}$ as

$$\underline{b} = \underline{b}_R + \underline{b}_N,$$

where $\underline{b}_R \in R(\underline{A})$ and $\underline{b}_N \in N(\underline{A}^T)$.

Now, let's expand:

$$\| \underline{A} \underline{x} - \underline{b} \|_2^2 = \| \underline{A} \underline{x} - \underline{b}_R - \underline{b}_N \|_2^2$$

$$\begin{aligned} &= \| \underline{A} \underline{x} - \underline{b}_R \|_2^2 - (\underline{A} \underline{x} - \underline{b}_R)^T \underline{b}_N \\ &\quad - \underline{b}_N^T (\underline{A} \underline{x} - \underline{b}_R) + \| \underline{b}_N \|_2^2. \end{aligned}$$

Note that $\underline{b}_N^T (\underline{A} \underline{x} - \underline{b}_R) = (\underline{A} \underline{x} - \underline{b}_R)^T \underline{b}_N = 0$

since $\underline{b}_N \in N(\underline{A}^T)$ and $\underline{A} \underline{x} - \underline{b}_R \in R(\underline{A})$,

and $R(\underline{A}) \perp N(\underline{A}^T)$.

So we have $\|\underline{A}\underline{x} - \underline{b}\|_2^2 = \|\underline{A}\underline{x} - \underline{b}_R\|_2^2 + \|\underline{b}_N\|_2^2$.

$\|\underline{b}_N\|_2^2$ is independent of $\underline{x}$, so

minimizing $\|\underline{A}\underline{x} - \underline{b}\|_2^2$ is the same

as minimizing $\|\underline{A}\underline{x} - \underline{b}_R\|_2^2$.

Note that $\|\underline{A}\underline{x} - \underline{b}_R\|_2^2 \geq 0$, and

there actually must be some $\underline{x}^*$

so that $\|\underline{A}\underline{x}^* - \underline{b}_R\|_2^2 = 0$ since $\underline{b}_R \in R(\underline{A})$.

It is not clear how to compute $\underline{b}_R$,

however, let's show that:

$$\underline{A}^T \underline{A} \underline{x}^* = \underline{A}^T \underline{b} \iff \underline{A} \underline{x}^* = \underline{b}_R.$$

($\Rightarrow$) If $\underline{A}^T \underline{A} \underline{x}^* = \underline{A}^T \underline{b}$, we plug in

$\underline{b} = \underline{b}_R + \underline{b}_N$ and get

$\underline{A}^T \underline{A} \underline{x}^* = \underline{A}^T \underline{b}_R$, implying:

$$\underline{A}^T (\underline{A} \underline{x}^* - \underline{b}_R) = \underline{0}. \quad \leadsto$$

This implies $\underline{A} \underline{x}^* - \underline{b}_R \in N(\underline{A}^T)$.

Since $\underline{A} \underline{x}^* - \underline{b}_R$ is also in $R(\underline{A})$,

the only possibility is that $\underline{A} \underline{x}^* - \underline{b}_R = \underline{0}$.

($\Leftarrow$) If $\underline{A} \underline{x}^* = \underline{b}_R$, then $\underline{A}^T \underline{A} \underline{x}^* = \underline{A}^T \underline{b}_R$.

Note that $\underline{A}^T \underline{b}_N = \underline{0}$, so

$$\underline{A}^T \underline{A} \underline{x}^* = \underline{A}^T \underline{b}_R + \underline{A}^T \underline{b}_N = \underline{A}^T \underline{b}.$$

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Geometry of the Normal Equations

We have: $\underline{A}^T \underline{A} \underline{x}^* = \underline{A}^T \underline{b}$,

which can be rewritten as:

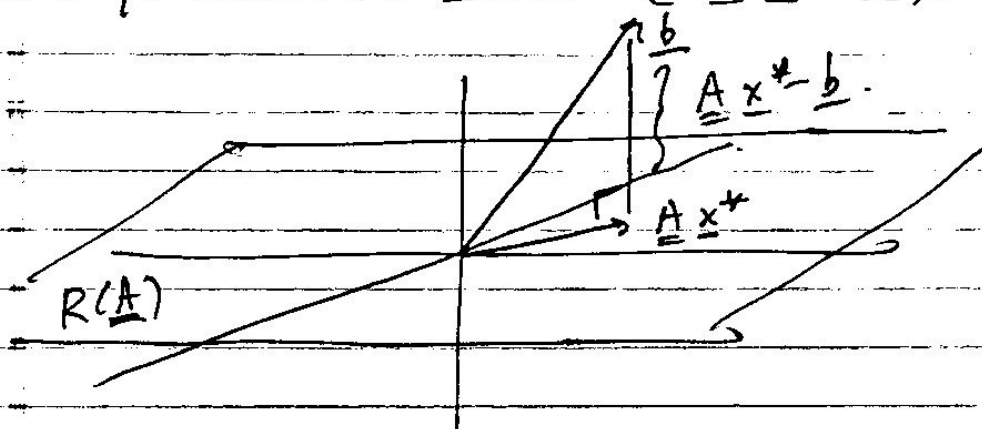
$$\underline{A}^T (\underline{A} \underline{x}^* - \underline{b}) = \underline{0}.$$

Take $\underline{y}$ arbitrary and consider

$$\underline{y}^T \underline{A}^T (\underline{A} \underline{x}^* - \underline{b}) = 0$$

$$\Leftrightarrow (\underline{A} \underline{y})^T (\underline{A} \underline{x}^* - \underline{b}) = 0.$$

Since y is arbitrary, this statement says $R(\underline{A}) \perp (\underline{A}\underline{x}^* - \underline{b})$.



Note that since $\underline{A} \in \mathbb{R}^{m \times n}$, $m \geq n$,

i.e. $\underline{A}$ is "tall and skinny," the

$R(\underline{A})$ is a low dimensional subspace of $\mathbb{R}^m$, hence it is very likely

$\underline{b}$ is not in the $R(\underline{A})$.

Observation: Since $\underline{A}^T \underline{A} \underline{x}^* = \underline{A}^T \underline{b}$,

assuming $\underline{A}^T \underline{A}$ is invertible, we have

$$\underline{x}^* = (\underline{A}^T \underline{A})^{-1} \underline{A}^T \underline{b} \Leftrightarrow \underline{A} \underline{x}^* = \underline{A} (\underline{A}^T \underline{A})^{-1} \underline{A}^T \underline{b}$$

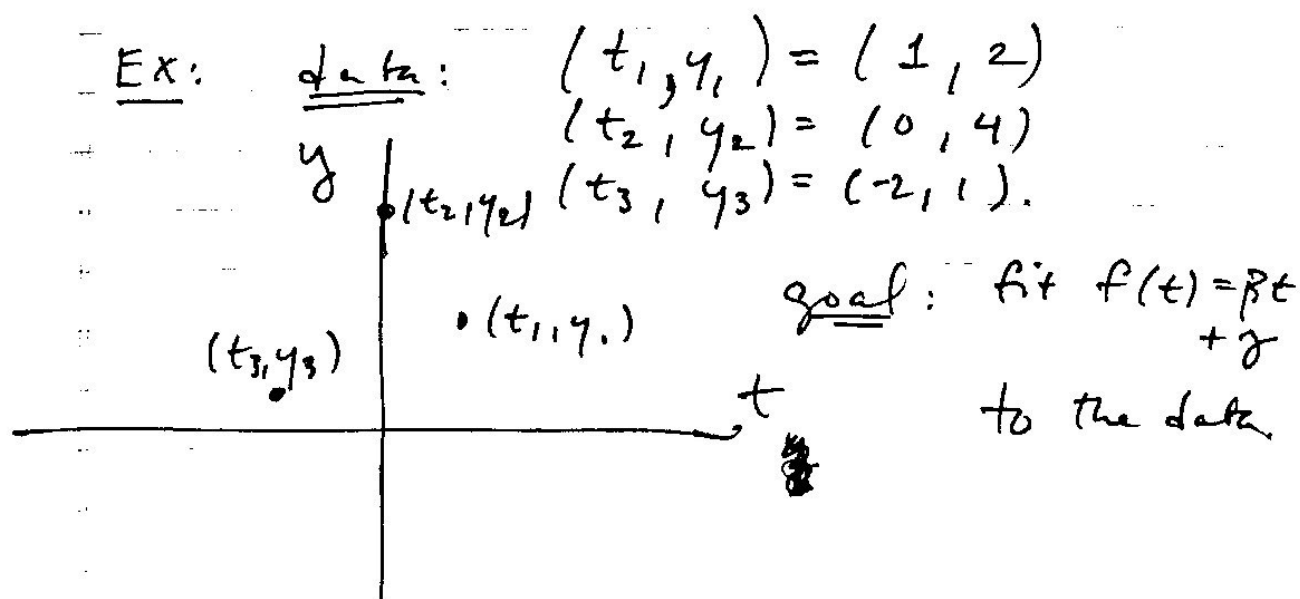
what type of matrix is $\underline{A} (\underline{A}^T \underline{A})^{-1} \underline{A}^T$?

Check: $\underline{P} = \underline{A} (\underline{A}^T \underline{A})^{-1} \underline{A}^T$ is an
orthogonal projector onto $R(\underline{A})$.

Question: Why is $\underline{A}^T \underline{A}$ likely
invertible? Hint: see that

$$N(\underline{A}) = N(\underline{A}^T \underline{A}).$$

If $N(\underline{A})$ contains more than just
the zero vector, then the very few
number of columns of $\underline{A}$ are linearly
dependent, which is "not likely."



We can set up.

$$\underline{b} = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix}, \quad \underline{A} = \begin{pmatrix} t_1 & 1 \\ t_2 & 1 \\ t_3 & 1 \end{pmatrix}, \quad \underline{x} = \begin{pmatrix} \beta \\ \gamma \end{pmatrix}.$$

$$\underline{A}^T \underline{A} = \begin{pmatrix} 1 & 0 & -2 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \\ -2 & 1 \end{pmatrix} = \begin{pmatrix} 5 & -1 \\ -1 & 3 \end{pmatrix}.$$

$$\underline{A}^T \underline{b} = \begin{pmatrix} 1 & 0 & -2 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 2 \\ 4 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 7 \end{pmatrix}.$$

$$\text{So, } \underline{x}^* = \begin{pmatrix} 5 & -1 \\ -1 & 3 \end{pmatrix}^{-1} \begin{pmatrix} 0 \\ 7 \end{pmatrix}.$$

$$\text{We solve } \begin{pmatrix} 5 & -1 \\ -1 & 3 \end{pmatrix} \begin{pmatrix} \beta \\ \gamma \end{pmatrix} = \begin{pmatrix} 0 \\ 7 \end{pmatrix}$$

$$\leadsto \begin{pmatrix} \beta^* \\ \gamma^* \end{pmatrix} = \begin{pmatrix} \frac{1}{2} \\ \frac{5}{2} \end{pmatrix}.$$

So, the line of best fit is

$$f(t) = \frac{1}{2}x + \frac{5}{2}.$$

Ex: data: $(t_1, y_1) = (0, 2)$
 $(t_2, y_2) = (-1, 5)$
 $(t_3, y_3) = (-2, 4)$
 $(t_4, y_4) = (1, 1)$

Goal: fit a parabola $g(t) = \gamma t^2 + \alpha t + \beta$ to the data.

$$\underline{b} = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{pmatrix} = \begin{pmatrix} 2 \\ 5 \\ 4 \\ 1 \end{pmatrix}$$

$$\underline{A} = \begin{pmatrix} t_1^2 & t_1 & 1 \\ t_2^2 & t_2 & 1 \\ t_3^2 & t_3 & 1 \\ t_4^2 & t_4 & 1 \end{pmatrix} \quad \underline{x} = \begin{pmatrix} \gamma \\ \alpha \\ \beta \end{pmatrix}$$

$$\Rightarrow \underline{A} = \begin{pmatrix} 0 & 0 & 1 \\ 1 & -1 & 1 \\ 4 & -2 & 1 \\ 1 & 1 & 1 \end{pmatrix}$$

Solve normal equations for $\underline{x}^* = \begin{pmatrix} \gamma^* \\ \alpha^* \\ \beta^* \end{pmatrix} \dots$