

11/12/2021

last time

→ introduction to eigenvalues/eigenvectors.

An eigenvector satisfies $\underline{A}\underline{v} = \lambda\underline{v}$ for $\underline{v} \neq \underline{0}$.

i.e. $(\underline{A} - \lambda \underline{I})\underline{v} = \underline{0}$.

Since $\underline{v} \neq \underline{0}$, $N(\underline{A} - \lambda \underline{I}) \neq \{\underline{0}\}$ and

from last class, this is equivalent to λ satisfying

$$p(\lambda) = \det(\underline{A} - \lambda \underline{I}) = 0.$$

$p(\lambda)$ = characteristic polynomial.

Ex: calculate eigenvectors/eigenvalues for

$$\underline{A} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}.$$

To compute eigenvalues, let's look at the characteristic polynomial

$$p(\lambda) = \det(A - \lambda I) = \det \begin{pmatrix} -\lambda & 1 \\ -1 & -\lambda \end{pmatrix}$$

$$\text{So } p(\lambda) = 0 \iff \lambda^2 + 1 = 0.$$

we see that $(\lambda^2 + 1) = (\lambda - i)(\lambda + i)$,

so the two roots of $p(\lambda)$ are

$$\lambda_1 = i, \quad \lambda_2 = -i.$$

To compute the eigenvector corresponding to $\lambda_1 = i$, we want to compute a basis for $N(A - \lambda_1 I) =$

$$N \left(\begin{pmatrix} -i & 1 \\ -1 & -i \end{pmatrix} \right).$$

$$\begin{pmatrix} -i & 1 \\ -1 & -i \end{pmatrix} \xrightarrow{\quad} \begin{pmatrix} -i & 1 \\ 0 & 0 \end{pmatrix}$$

Multiply row 1 by i ,
add to row 2, and put result
in row 2.

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$$S_1, \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \in N(\underline{A} - \underline{\lambda}_1 \underline{I}) \quad \text{i.f.}$$

$$\begin{pmatrix} -i & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Leftrightarrow \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = x_2 \begin{pmatrix} -i \\ 1 \end{pmatrix}.$$

$$\text{So } \underbrace{\begin{pmatrix} -i \\ 1 \end{pmatrix}}_{= \underline{v}_1}, \underbrace{i}_{= \lambda_1} \text{ is the first eigenvector.}$$

$$\text{For } \lambda_2 = -i, \text{ we compute } N\left(\begin{pmatrix} i & 1 \\ -1 & i \end{pmatrix}\right)$$

$$\begin{pmatrix} i & 1 \\ -1 & i \end{pmatrix} \xrightarrow{\quad} \begin{pmatrix} i & 1 \\ 0 & 0 \end{pmatrix}$$

Multiply 1st row by $-i$, add to 2nd row, and put result in 2nd row

$$S_1, \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \in N\left(\begin{pmatrix} i & 1 \\ -1 & i \end{pmatrix}\right) \Leftrightarrow$$

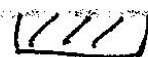
$$\begin{pmatrix} i & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}.$$

$$\Leftrightarrow \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = x_2 \begin{pmatrix} i \\ 1 \end{pmatrix}$$

So $\left(\begin{pmatrix} i \\ 1 \end{pmatrix}, -i \right)$ is the second eigenvector.
 $\underline{v_2} = \underline{v_2} \quad \underline{\lambda_2} = \underline{\lambda_2}$

Remark: Complex eigenvalues usually mean some sort of oscillations.

Ex: Simple harmonic oscillator



$\hookrightarrow$ Spring
 m mass

Equations of motion

$$m \frac{d^2 x}{dt^2} = -kx$$

$x =$ displacement of the spring.

Consider the simple case $m=k=1$.

$$\frac{d^2 x}{dt^2} = -x$$



Introduce a new variable, the velocity:

$$v = \frac{dx}{dt}.$$

Then,

$$\frac{d^2x}{dt^2} = -x \Leftrightarrow \begin{cases} \frac{dx}{dt} = v \\ \frac{dv}{dt} = -x \end{cases}$$

$$\Leftrightarrow \frac{d}{dt} \begin{pmatrix} x \\ v \end{pmatrix} = \begin{pmatrix} v \\ -x \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} x \\ v \end{pmatrix}.$$

Ex: Compute eigenvectors/values of $A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$.

$$\text{we look at } p(\lambda) = \det \begin{pmatrix} 1-\lambda & 1 \\ 0 & 1-\lambda \end{pmatrix}.$$

$$p(\lambda) = 0 \Leftrightarrow (1-\lambda)^2 = 0.$$

Since $\lambda_1 = 1$ is a double root,

we say λ_1 has algebraic multiplicity 2

To compute the eigenvectors, we look for a basis for $N(\underline{A} - \lambda_1 \underline{I}) = N(\underline{A} - \underline{I})$.

$$\underline{A} - \underline{I} = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}.$$

$$\text{so } \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \in N(\underline{A} - \underline{I}) \Leftrightarrow \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = x_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}.$$

so, $\left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right\}$ is a basis for $N(\underline{A} - \underline{I})$.

$\dim N(\underline{A} - \underline{I}) = 1 = \text{geometric multiplicity of } \lambda_1$.

Diagonalization of a matrix.

let $\lambda_1, \dots, \lambda_n, \underline{v}_1, \dots, \underline{v}_n$ be the eigenvalues and eigenvectors of $\underline{A} \in \mathbb{R}^{n \times n}$,

$$\text{so } \underline{A} \underline{v}_i = \lambda_i \underline{v}_i, \quad i = 1, \dots, n.$$

In matrix form, the n equations are:

$$\begin{pmatrix} | & | & \dots & | \\ \underline{A} \underline{v}_1 & \underline{A} \underline{v}_2 & \dots & \underline{A} \underline{v}_n \\ | & | & \dots & | \end{pmatrix} = \begin{pmatrix} | & | & \dots & | \\ \lambda_1 \underline{v}_1 & \lambda_2 \underline{v}_2 & \dots & \lambda_n \underline{v}_n \\ | & | & \dots & | \end{pmatrix}.$$

This matrix equation can be rewritten as:

$$\underline{A} \underbrace{\begin{pmatrix} | & & | \\ \underline{v}_1 & \dots & \underline{v}_n \\ | & & | \end{pmatrix}}_{=\underline{V}} = \underbrace{\begin{pmatrix} | & & | \\ \underline{v}_1 & \dots & \underline{v}_n \\ | & & | \end{pmatrix}}_{=\underline{V}} \underbrace{\begin{pmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & & \ddots \\ & & & \lambda_n \end{pmatrix}}_{=\underline{\Lambda}}$$

$$\Leftrightarrow \underline{A} \underline{V} = \underline{V} \underline{\Lambda}$$

If the eigenvectors are linearly independent, then $\underline{V}$ is invertible, and

$$\underline{A} = \underline{V} \underline{\Lambda} \underline{V}^{-1}$$

diagonalization of $\underline{A}$.

Ex: last time, for $\underline{A} = \begin{pmatrix} 1 & 2 \\ 2 & 4 \end{pmatrix}$,

we found eigenpairs $\left(\begin{pmatrix} -2 \\ 1 \end{pmatrix}, 0 \right), \left(\begin{pmatrix} 1 \\ 1 \end{pmatrix}, 5 \right)$.

so:

$$\underline{A} \begin{pmatrix} -2 & 1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} -2 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 0 & 5 \end{pmatrix}$$

$$\begin{pmatrix} -2 & \frac{1}{2} \\ 1 & 1 \end{pmatrix}^{-1} = \frac{1}{-2 - \frac{1}{2}} \begin{pmatrix} 1 & -\frac{1}{2} \\ -1 & -2 \end{pmatrix}$$

$$= -\frac{2}{5} \begin{pmatrix} 1 & -\frac{1}{2} \\ -1 & -2 \end{pmatrix}$$

$$S_0 \quad \underbrace{\begin{pmatrix} 1 & 2 \\ 2 & 4 \end{pmatrix}}_{= \underline{\underline{A}}} = \underbrace{\begin{pmatrix} -2 & \frac{1}{2} \\ 1 & 1 \end{pmatrix}}_{\underline{\underline{V}}} \underbrace{\begin{pmatrix} 0 & 0 \\ 0 & 5 \end{pmatrix}}_{\underline{\underline{\Lambda}}} \underbrace{\begin{pmatrix} -\frac{2}{5} & \frac{1}{5} \\ \frac{2}{5} & \frac{4}{5} \end{pmatrix}}_{\underline{\underline{V^{-1}}}}$$