

11/29/2021

last time:

~ construction of the SVD.

$$\underline{A} \in \mathbb{R}^{m \times n} \dots$$

$$\underline{A} = \underbrace{\begin{pmatrix} | & & | \\ \underline{u}_1 & \dots & \underline{u}_m \\ | & & | \end{pmatrix}}_{\underline{U}} \underbrace{\begin{pmatrix} \sigma_1 & \dots & \sigma_r & 0 \\ 0 & & 0 & \end{pmatrix}}_{\underline{\Sigma}} \underbrace{\begin{pmatrix} \xrightarrow{\underline{v}_1} \\ \vdots \\ \xrightarrow{\underline{v}_n} \end{pmatrix}}_{\underline{V}^T}$$

$\underline{U}, \underline{V}$ orthogonal.

$\underline{u}_1, \dots, \underline{u}_r$ are eigenvectors of $\underline{A} \underline{A}^T$ with
eigenvalues of $\sigma_1^2, \dots, \sigma_r^2$.

$\underline{v}_1, \dots, \underline{v}_r$ are eigenvectors of $\underline{A}^T \underline{A}$ with
eigenvalues of $\sigma_1^2, \dots, \sigma_r^2$.

$\underline{u}_{r+1}, \dots, \underline{u}_m$ and $\underline{v}_{r+1}, \dots, \underline{v}_n$ are eigenvectors
of $\underline{A} \underline{A}^T$ and $\underline{A}^T \underline{A}$ with an eigenvalue
of zero.

Ex: $\underline{A} = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix}$.

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} = \underbrace{\begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{pmatrix}}_{\underline{U}} \underbrace{\begin{pmatrix} \sqrt{6} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}}_{\underline{\Sigma}} \underbrace{\begin{pmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{6}} & -\frac{2}{\sqrt{6}} \end{pmatrix}}_{\underline{V}^T}$$

Observe: $\text{rank } \underline{A} = \dim R(\underline{A}) = 1$,
and # of nonzero singular values = 1.

In general: $\text{rank } \underline{A} = \begin{pmatrix} \# \text{ of nonzero} \\ \text{singular values} \end{pmatrix}$.

Procedure for computing SVD $\underline{A} \in \mathbb{R}^{m \times n}$.

① compute $\lambda_1 \geq \dots \geq \lambda_m$, the eigenvalues of $\underline{A} \underline{A}^T$ with r eigenvectors $\underline{u}_1, \dots, \underline{u}_m$.
orthonormal.

let $r =$ largest index such that $\lambda_r > 0$.

ret $\underline{U} = \begin{pmatrix} | & & | \\ \underline{u}_1 & \dots & \underline{u}_m \\ | & & | \end{pmatrix}$.

② compute $\sigma_j = \sqrt{\lambda_j}$, $j = 1, \dots, r$.

③ Compute $\underline{v}_j = \sigma_j^{-1} \underline{A}^T \underline{u}_j$, $j=1, \dots, r$.

Compute $\{\underline{v}_{r+1}, \dots, \underline{v}_n\}$ as an orthonormal basis for $N(\underline{A}^T \underline{A}) = N(\underline{A})$.

set $\underline{V} = \begin{pmatrix} \underline{v}_1 & \dots & \underline{v}_n \end{pmatrix}$.

④ $\underline{A} = \underline{U} \underline{\Sigma} \underline{V}^T$, where $\underline{\Sigma} = \begin{pmatrix} \sigma_1 & & 0 \\ & \ddots & \\ 0 & \sigma_r & 0 \\ & & 0 \end{pmatrix}$.

Ex: compute the SVD of $\underline{A} = \begin{pmatrix} 1 & 2 & 2 \\ 2 & 2 & 1 \end{pmatrix}$.

① Diagonalization of $\underline{A} \underline{A}^T$ is

$$\underbrace{\begin{pmatrix} 9 & 8 \\ 8 & 9 \end{pmatrix}}_{\underline{A} \underline{A}^T} = \underbrace{\begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{pmatrix}}_{\underline{U}} \underbrace{\begin{pmatrix} 17 & 0 \\ 0 & 1 \end{pmatrix}}_{\underline{\Sigma}} \underbrace{\begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{pmatrix}}_{\underline{V}^T}$$

so $\lambda_1 = 17$, $\lambda_2 = 1$, and

$$\underline{u}_1 = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix}, \quad \underline{u}_2 = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{pmatrix}.$$

(2) compute $\sigma_1 = \sqrt{\lambda_1} = \sqrt{17}$.

$\sigma_2 = \sqrt{\lambda_2} = 1$.

(3) compute $v_1 = \frac{1}{\sigma_1} A^T u_1 = \frac{1}{\sqrt{34}} \begin{pmatrix} 3 \\ 4 \\ 3 \end{pmatrix}$.

$v_2 = \frac{1}{\sigma_2} A^T u_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$.

v_3 is computed as the normalized basis vector for $N(A)$.

$v_3 = \begin{pmatrix} \frac{2}{\sqrt{17}} \\ -\frac{3}{\sqrt{17}} \\ \frac{2}{\sqrt{17}} \end{pmatrix}$.

so: $\begin{pmatrix} 1 & 2 & 2 \\ 2 & 2 & 1 \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} \sqrt{17} & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$

$\star \begin{pmatrix} \frac{3}{\sqrt{34}} & \frac{4}{\sqrt{34}} & \frac{3}{\sqrt{34}} \\ -\frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ \frac{2}{\sqrt{17}} & -\frac{3}{\sqrt{17}} & \frac{2}{\sqrt{17}} \end{pmatrix}$

$\Rightarrow V^T$

SVD and FTLA

We already have a basis for $N(\underline{A})$ by construction, i.e.

$$N(\underline{A}) = \text{span}(\underline{v}_{r+1}, \dots, \underline{v}_n).$$

$$\text{Fact: } R(\underline{A}) = \text{span}(\underline{u}_1, \dots, \underline{u}_r).$$

Pf: we see that

$$\underline{A} = \underline{U} \underline{\Sigma} \underline{V}^T = \sum_{j=1}^r \sigma_j \underline{u}_j \underline{v}_j^T.$$

Take $\underline{y} \in R(\underline{A})$. Then $\underline{y} = \underline{A} \underline{x}$ for some $\underline{x}$.

$$\text{but } \underline{y} = \underline{A} \underline{x} = \sum_{j=1}^r (\sigma_j \underline{v}_j^T \underline{x}) \underline{u}_j \in \text{span}(\underline{u}_1, \dots, \underline{u}_r),$$

$$\text{so } R(\underline{A}) \subset \text{span}(\underline{u}_1, \dots, \underline{u}_r).$$

To see the reverse containment,

$$\text{look at } \underline{A} \underline{v}_i = \sum_{j=1}^r \sigma_j \underline{u}_j \underline{v}_j^T \underline{v}_i = \sigma_i \underline{u}_i,$$

$$\text{so we have } \underline{u}_i = \underline{A} \left(\frac{1}{\sigma_i} \underline{v}_i \right) \text{ implying}$$

$$\underline{u}_i \in R(\underline{A}). \text{ Thus, } \text{span}(\underline{u}_1, \dots, \underline{u}_r) \subset R(\underline{A}).$$

Using the fact that the SVD of A^T is

$$\underline{A}^T = (\underline{U} \underline{\Sigma}^T \underline{V}^T)^T = \underline{V} \underline{\Sigma} \underline{U}^T,$$

we can conclude:

$$\begin{aligned} N(\underline{A}^T) &= \text{span}(\underline{u}_{r+1}, \dots, \underline{u}_m) \\ R(\underline{A}^T) &= \text{span}(\underline{v}_1, \dots, \underline{v}_r). \end{aligned}$$

Main Point: Singular vectors can be used to construct orthonormal bases for the four fundamental subspaces.